

(COI) (POI)

(CO) (PO2)

[10]

(CO1) (PO2)

[20]

(COD (PO3)

15)

Program: B.Sc. Engg. (IPE) Date: 06 October 2023 Semester: 5th Sem. Time: 10:30 am - 12:00 pm (Morning)

ISLAMIC UNIVERSITY OF TECHNOLOGY (IUT) ORGANISATION OF ISLAMIC COOPERATION (OIC)

DEPARTMENT OF MECHANICAL AND PRODUCTION ENGINEERING

Winter Semester, A. V. 2022-2023 Course No.: IPE 4513 Time: 1 Hours 30 Min(s) Full Marks: 75

There are 3 (Three) questions, Answer all the questions, Marks of each question and corresponding CO and PO are written in the brackets. Do not write on this question paper.

1. a) Draw a flow diagram of design processes involved in a product cycle and describe its COD

steps. (PO1) 1101

b) Classify and describe different types of orthographic projections with necessary illustration

2. a) There are two coordinate systems X1Y1Z1 and X1Y2Z2, where Z2 is opposite of Y1, X2 is

parallel with Z_1 , and Y_2 is opposite of X_1 . The origin O_2 when measured in $X_1Y_1Z_1$ is (7, 5, 0). The X₁Y₁Z₁ coordinates of point P is (3, 0, 2). With respect to $X_1Y_1Z_1$, using the standard $Rot(x,\theta)$, $Rot(y,\theta)$, $Rot(z,\theta)$ and

Trans(a,b,c) to derive the transformation T* that will transform the rigid body of $X_2Y_2Z_2$ to coincide with $X_1Y_1Z_1$.

(iii) Calculate $P^* = T^* \cdot I3 \cdot 0 \cdot 2 \cdot II^T$.

Is T^* the T_{res} or T_{res} ? b) How is the Oct-tree representation computed? Explain why the octree representation

requires less memory space than the voxel repetition for the same resolution. 3. a) For a non-periodical and uniform B-spline curve of order 3 defined by the control points Po. P1, P2, and P3. There are two independent curves comprising this B-spline, each

defined on the parameter range u∈[0,1] and u∈[1,2] respectively. Expand the B-spline curve equation to get the equation of the second segment. b) How do you measure the degree "smoothness" of a curve? What is the minimum

acceptable curve for engineering design and why? (COD (PO2)