

ISLAMIC UNIVERSITY OF TECHNOLOGY (IUT)  
ORGANISATION OF ISLAMIC COOPERATION (OIC)  
DEPARTMENT OF ELECTRICAL AND ELECTRONIC ENGINEERING

Mid-Semester Examination  
Course No.: EEE 4631  
Course Title: Power System III

Summer Semester, A. Y. 2022-2023  
Time: 90 Minutes  
Full Marks: 75

There are 3 (three) questions. Answer all 3 (three) questions. The symbols have their usual meanings. Programmable calculators are not allowed. Marks of each question and corresponding COs and POs are written in the brackets.

1. a) Figure 1 represents the cross-sectional view of a synchronous machine under loaded condition. i) Locate the various mmf axes by providing appropriate dot and cross signs as per your choice. ii) Locate and explain the concept of  $\theta_m$ . iii) Calculate the corresponding electrical angle of  $\theta_m$ . iv) Sketch the corresponding phasor diagram considering zero armature resistance. 15  
(CO1,  
PO1)

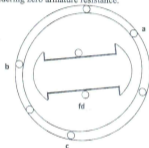


Figure 1

- b) Explain the necessity of representing the rotor position with respect to a rotating reference frame with a neat diagram. 5  
(CO1,  
PO1)
- c) Mention the range of rotor angle for generation mode of operation. Justify your answer. 5  
(CO2,  
PO2)
2. a) The fuel-cost functions for two thermal plants in Tk./h are given by 18  
(CO3,  
PO2)
- $$C_1(P_1) = 561 + 7.92P_1 + 0.001562P_1^2$$
- $$C_2(P_2) = 310 + 7.85P_2 + 0.00194P_2^2$$
- and the line loss is represented as  $P_{\text{loss}} = 0.00003P_1^2 + 0.00009P_2^2$  where  $P_1$  and  $P_2$  are in kW. The total demand is 850 kW. Neglecting the generator limits, find the optimal dispatch and the total power loss. (Maximum three iterations).
- b) The swing equation is given by  $\frac{d^2\delta}{dt^2} = \frac{\omega_s}{2H} (P_m - P_{\text{max}} \sin \delta)$ . Derive the linearized swing equation without incorporating the damping power. 7  
(CO1,  
PO1)

3. Assume the rotor position, of the system shown in Figure 3, with respect to a stationary frame of reference after 1 second is 55 radians. The angular velocity of a synchronously rotating reference frame is  $\alpha$  rpm. A 50 Hz two pole synchronous generator having inertia constant  $H=9.94$  MJ/MVA is connected to an infinite bus through a purely reactive circuit as shown in Figure 3. Reactances are marked on the diagram on a common system base. Assume per unit damping power coefficient is equal to  $\beta$ . Find the values of a) damping ratio, b) natural frequency of oscillation and c) determine the stability of the system by calculating the roots of the system when

- $\alpha = 500$  rpm,  $\beta = 0.14$
- $\alpha = 520$  rpm,  $\beta = 0.14$
- $\alpha = 520$  rpm,  $\beta = -0.14$

[NB: Formula for converting RPM to radian is given by  $\omega_{(rad/s)} = \frac{2\pi \times RPM}{60}$ ]



Figure 3